



# Error Control Methods for UAV Multimedia Communication Batoul Sarvi

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# **Motivation**

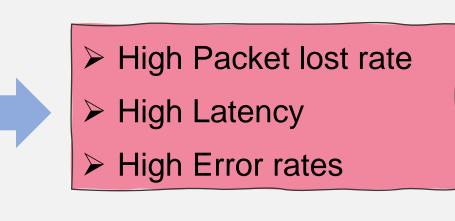
- Reliable streaming Multimedia communications in UAV scenarios
- Applications such as environment monitoring, precision agriculture, search and rescue operation, target tracking, and firefighting.



### **Research Plan**

- There is no method using adaptive hybrid AP-ARQ/AP-FEC in for Multimedia communication on UAV networks.
- ➢ Using a Hybrid AP-ARQ/FEC with dynamic redundancy provide more reliability, less latency, and less energy consumption.
- ➢ Design an algorithm Focus on Cross layer solution for improve reliability:
  - Dynamic redundancy for FEC in Application layer
    - Determine Redundancy based on Optimization / Machine learning Solutions
  - Using Hybrid ARQ/FEC in Link Layer
    - Modulation Coding Schemes

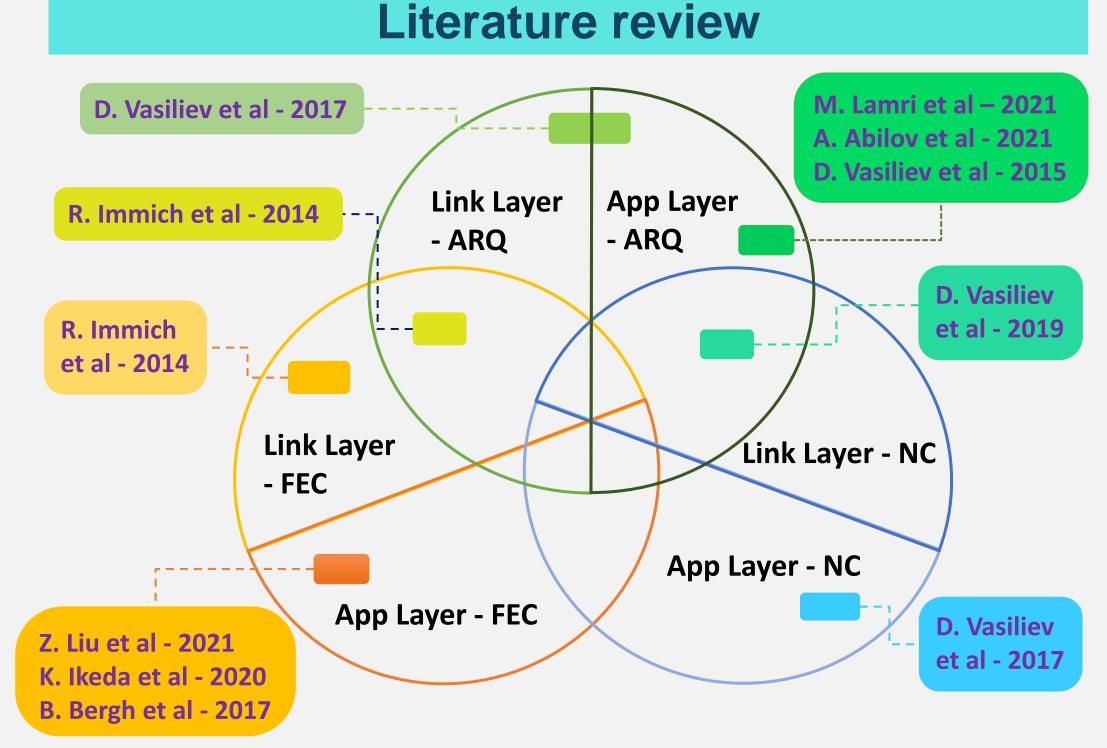
- High mobility
- High volume of the compressed video stream
- limited battery



# **Methodologies**

#### Classical Error Control & Recovery Methods

- Automatic Repeat Request (ARQ)
- Forward Error Correction (FEC)
- Network Coding (NC)
- Discrete-event simulation



- Queuing management
- Unequal Error Protection on Application and Link Layers
- Changing Video Encoding rate during stream
  - Based on the packet lost rate
- ➢ Evaluating on NS3.
- ➢ Suitable for Multi-drone scenarios.
- $\blacktriangleright$  Investigating proposed method for cellular network.

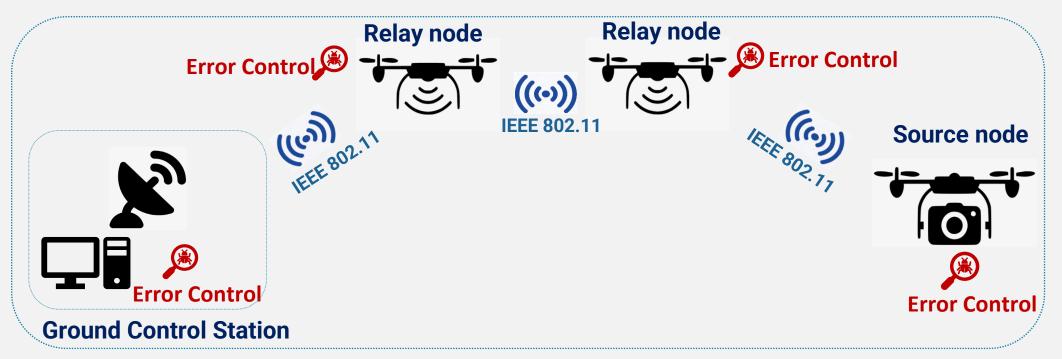


Fig. 1: Envisaged final vision of error control methods for UAV communication

### **UN SDG challenges**

The purpose of this study is to develop a reliable infrastructure for UAV networks.

Real-time video streaming provided by this project opens significant opportunities in a wide range of fields such as:

- Smart agriculture with monitoring field by drones.
- Monitoring and protecting jungles and the environment particularly those are unreachable.



- Using static / predefine multiple state for redundancy in FEC.
- Static number of retransmission in ARQ.
- Using broadcast mechanism in AP-FEC
- NC is suitable for relay UAV node.

- Smart cities such as mobile surveillance systems by drones.
- Sustainable communication based on UAVs.
- Monitoring resource water and avoiding wasting water.



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